

The above specifications are subject to change and some models may be discontinued

※Be sure to follow cautions written in the instruction manual, user manual, and the

without notice.

technical descriptions (catalog, homepage).

Model		SPR1-1	SPR1-2	SPR1-3	SPR1-4	1			
Control ph	250	Single-phase	3FR1-2	JFRI-JLLLL	3FR1-4				
	voltage (50/60Hz)	<u> </u>	220VAC~	380VAC~	440VAC~				
Power sup		100-240VAC~ 50		1000 VAO -	1100/10				
Min. load		1A	100112				_		
		90 to 110% of rate	d voltage		18	}			
Power cor		<ul> <li>Rated load curre</li> </ul>	nt 25A/35A/50A: m nt 70A/100A/150A:						
Display m	ethod	3-digit 7-segment		2		81 1607 BAS 343	Laturks		
	ctriod		or/Manual control	3		8.8.1	<b>3</b> X <b></b>		
Indicator			utput indicator/unit	5		900			
Control m	ethod	Phase control: normal control mode, constant current/constant voltage/ constant power feedback control mode     Cycle control: fixed cycle control mode, variable cycle control mode     ON/OFF control							8
Applied load		Phase control, ON/OFF control: resistance load, inductive load     Cycle control: resistance load							
Control input		<ul> <li>Auto control: DC4-20mA, 1-5VDC=, ON/OFF contact (no-voltage input), pulse voltage (5-12VDC=)</li> <li>Manual control: outside adjuster (10kΩ), inside adjuster (output limit)</li> </ul>							-
Digital inp	ut (DI)	RUN/STOP switch	ning, AUTO/MAN s	witching, RESET					
Output	Alarm	$250VAC\sim$ 3A, 30	VDC= 3A, 1c resis	tive load					
Output	Communication	RS485 communica	tion output (Modbus	12					
Output rar	nge	Phase control: 0 to	98% · Cycle contro	1: 0 to 100% • ON/OF	F control: 0%, 100%	Ĭ	1-1		<b>74</b> 10 🖻
Output accuracy		Normal control: within ±10% F.S. of rated load voltage     Constant current feedback control: within ±3% F.S. of rated load voltage     Constant voltage feedback control: within ±3% F.S. of rated load voltage     Constant power feedback control: within ±3% F.S. of rated load power						)	
Set metho	d	By front keys, by co	ommunication						
Functions		Output limit (OUT ADJ), AUTO/MAN selection, control method selection, RESET, SOFT START, SOFT UP/DOWN, output high/low limit, input correction, input slope correction, monitoring (control input, load voltage/current/power/resistance, power supply frequency, heatsink temperature)					<ol> <li>Bracket</li> <li>Indicator</li> </ol>		
	Alarm	Overcurrent alarm, overvoltage alarm, fuse break alarm, SCR error alarm, heater break alarm, heatsink overheat alarm					Indicat RUN		eration indicator
Cooling m	ethod		t 25A/35A/50A: nat t 70A/100A/150A: f	ural cooling orced air cooling (wi	th the cooling fan)		MAN		nual control indica
Insulation	resistance	Over 200MQ (at 5	00VDC megger)				ALM	_	rm indicator
Dielectric	strength	2,000VAC 50/60H	z for 1 min (betwee	en input terminals a	nd power terminals)		OUT		tput indicator
Output lea	kage current	Max. 10mArms				3	Display		Displays settings of parameter and set
Noise imm	nunity	±2kV the square v	vave noise (pulse v	vidth: 1µs) by the no	pise simulator	4	Unit ind		
Memory re	etention	Approx. 10 years	(when using non-ve	platile semiconducto	or memory type)		(🏹: Lię	ght ON	I/●: Light OFF)
\/ibrati	Mechanical	0.75mm amplitude	at frequency of 5 to	55Hz in each X, Y, Z	direction for 2 hours		Indicat		Display
Vibration	Malfunction	0.5mm amplitude a	t frequency of 5 to 5	5Hz in each X, Y, Z	direction for 10 min		V	A	
Environ	Ambient temp.	-10 to 55°C, storage	ge: -20 to 80°C				•	•	Resistance, inpu
ment	Ambient humi.	35 to 85%RH, sto	rage: 35 to 85%RH				¢	• ·	Voltage Current
Accessory	1	11-pin connector					Å	<del>V</del> Ö	Power
Approval		CE							
Approval Weight <sup>⊛1</sup>		Rated load current 25A/35A/50A: approx. 1.6kg (approx. 1.3kg)     Rated load current 70A: approx. 1.65kg (approx. 1.35kg)     Rated load current 100A/150A: approx. 3.2kg (approx. 2.8kg)							



Dimensions Rated load current 25A/35A/50A









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High Temperature Caution While supplying power to the load or right after turning off the power of the load, do not touch the body and heatsink. Failure to follow this instruction may result in a burn due to the high temperature.

Rated currer 25A 35A

※The



ed load ent	Model	Rated load current	Model	Rated load current	Model			
	50FE	50A	80ET	100A	FWH-150B			
	63ET	70A	100FE	150A	FWH-200B			
e performance of the product is guaranteed only when using the fuse provided by us.								

## Parameter Group

%Hold the MODE key in RUN mode to enter into parameter group.

 $\times In$  parameter setting group, press the  $\underline{\texttt{MODE}}$  key to move to other parameter in the group. %Press the MODE key once after changing the setting value, to save the setting value and move to the

next paramete When entering to the parameter, press the Ҝ key to move digit, 🗵, 🗟 keys to change the setting

value. XIf there is no key input for 30 sec while setting SV or the parameters, the new settings are ignored, and

the unit will return to RUN mode with previous settings. %Hold the MODE key for 3 sec to save the setting value and return to RUN mode after changing the

	RUN mode	
MODE	MODE 2 sec	MODE 4 sec
Monitoring group	Parameter 1 group [PR I]	Parameter 2 group [PR2]

	ittoring group			
Display	Measuring range	Description	Unit	Factory default
In	0 to 100	Displays the present control input as percentage.	%	—
L-u *1	0 to rated voltage range	Displays the present load voltage.	V	—
L-8 *1	0 to rated current range	Displays the present load current.	A	_
L-2 *1	0 to rated power range	Displays the present load power.	kW	_
L-r *1	0 to 100	Displays the present resistance as percentage compared to the set resistance of full load auto recognition.	%	_
ΕñΡ	0 to 100	Displays the present temperature of heatsink.	°C	—
Fr9	50, 60	Displays the present frequency of power supply.	Hz	_

### Load Output Formula

Туре	Input		Display	y	Formula
Auto control (AUTO)	Current	DC4-20mA		420	Load output [%]
	Voltage	1-5VDC	Int	1-5	= Control input [%] × Output slope (5LP) [%]
	RS485 communication		1	Eoñ	Load output [%] = RS485 [%]
Manual control (MAN)	Output	Inside adjuster		1 _ r	Load output [%] = Inside adjuster [%]
		Outside adjuster		E_r	Load output [%] = Outside adjuster [%]
	limit	Inside/outside adjuster		E _ I	Load output [%] = Inside adjuster [%] × Outside adjuster [%]

# Comprehensive Device Management Program [DAQMaster]

DAQMaster is a comprehensive device management software for setting parameters and monitoring

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Item	Minimum specifications
System	IBM PC compatible computer with Pentium III or above
Operations	Windows 98/NT/XP/Vista/7/8/10
Memory	256MB+
Hard disk	1GB+ of available hard disk space
VGA	Resolution: 1024×768 or higher
Others	RS232C serial port (9-pin), USB port

### User Manual for Communication

For the detail information and instructions, please refer to user manual for communication, and be sure to follow cautions written in the technical descriptions (catalog, homepage). Visit our homepage (www.autonics.com) to download manuals.

### RS485 Communication Output

\*Applicable for models with RS485 communication output through option output (SPR1-\_\_\_T\_\_). Please refer to I Ordering Information

Comm. protocol	Modbus RTU	O	2400, 4800, 9600, 19200,	
Connection method	RS485	Comm. speed	38400 bps	
Application standard	Compliance with EIA RS485	Comm. response time	5 to 99ms (default: 20ms)	
Max. connections	31 units (address: 1 to 99)	Start bit	1-bit (fixed)	
Synchronization method	Asynchronous	Data bit	8-bit (fixed)	
Comm. method	Two-wire half duplex	Parity bit	None, Even, Odd	
Comm. distance	Max. 800m	Stop bit	1-bit, 2-bit	

Terminating

### 2. Application of system organization



%It is recommended to use Autonics communication converter; SCM-WF48 (Wi-Fi to RS485-USB wireless) communication converter, sold separately), SCM-US48I (USB to RS485 converter, sold separately), SCM-38I (RS232C to RS485 converter, sold separately). Please use twisted pair wire, which is suitable for RS485 communication, for SCM-WF48, SCM-US48I and SCM-38I.

Para	interer	i gro	up [ F A I]								
Display	Setting r	ange		Description						Unit	Factory
5-E	0 to 100	-			OFT ST	ART tir	ne			sec	default 3
U-F	0 to 100			<u> </u>	OFTU					sec	3
d-E	0 to 100				OFT D		20			sec	3
	010100			<u> </u>			mit value.			%	0
L-L H-L	0 ≤ L - L	≤H-L	≤ 100	<u> </u>			imit value.			%	+
						<u> </u>		et the output	elon		100
5LP *2	0 to 100			In case of auto control (AUTO), set the output slop limit proportional to control input for limit load power.						%	100
🔿 Para	meter	2 arc	oup [ PR2 ]								
Display	Setting r	-	ab[////]	Desc	ription					Unit	Factory
	420	DC4-	20m∆		-						default
	1-5	1-5VE									
1 n E <sup>**2</sup>	5 12	5-12V	/DC	Set th	ne contr	ol input	specification	1.		-	420
	onF		FF contact								
	Eoñ		5 comm.								-
	PR	Phase - Norr	e control nal								
		Phase	e control								
	u-F <sup>%1</sup>		stant voltage								
		feedback Phase control									
	[-F *1	- Con	stant current								
[-ñ			back	Set #	ne contr	ol meth	od.			_	PR
	U-F *1		e control stant power				-				
		feed	back								
	F - [	- Fixed cycle									
	u-C										
	onF	ON/O	FF control								
	1		e adjuster								
ñ∏n <sup>%2</sup>	E_r		de adjuster e/Outside	In cas		nual co	ntrol (MAN), s	et the output I	imit	-	1_1
	E_!	adjus			notiou.						
*2								for the offset			
1 nb ^*	-99 to 99	9			een the value.	actual i	nput value ar	nd the measu	red	%	0.0
					Set the compensated input slope value between the						+
5Pn <sup>%2</sup>	-99 to 99				actual input value 100% and the measured input value 100%.					%	0.0
		Resist	tance and	100 /						<u> </u>	-
	In	input									
d1 5	L-u *1				ne desir ay part.	ed valu	e to be displa	ayed at the fro	ont	-	In
	L-A *1			aispic	iy pure.						
e ×1	L-Y *1		power	0.1.1							
οΕυ *1 οΕ± <sup>*1</sup>	0 to 120 0 to 100			Set the overcurrent alarm value. Set the overcurrent alarm delay time.					% sec	120	
000 *1	0 to 120						alarm value.	into.		%	120
out <sup>×1</sup>	0 to 100			Set the overvoltage alarm delay time.					sec	5	
- *1				It executes 100% control output for 3 sec and the load							
F-[	oFF / or	1		resistance value recognized automatically as the initial set when the function is ON.					-	oFF	
НЬ⊔ <sup>Ж1</sup>	oFF / 10	) to 10	D	Set the heater break alarm value.					%	10	
Adr <sup>%3</sup>	01 to 99			Assig	in the ur	nique a	ddress when	communicati	ng.	—	01
ь₽5 <sup>жз</sup>	24, 48, 9	96, 192	, 384	Set the speed of data transmission. Multiply by 100 to read the set value. (e.g.: 96=9600bps)					bps	96	
				A parity bit is a data communication method that adds					-	-	
Prt <sup>*3</sup>	non / Eu	E / od	d	an ac	an additional bit to each character in transmitted data					-	000
								a loss and co		-	+
5EP **3	1, 2				ne numb string.	er of bi	is to mark the	e end of a tra	ismitted	bit	2
har"				Set s	tandby t			munication er			
r⊻£ <sup>≪3</sup>	5 to 99				commu etc.).	inicatin	g with a slow	master devic	æ (PC,	ms	20
	EnA	Enabl	e	/	,	able th	e setting of p	arameters sto	ored in		+
Eñy *3				mem	ory via d	commu	nication from	the master sy	ystem	_	EnR
	d 5.A	Disab	le		PLC, et /s possi		aing the set	value in para	meter is		
	oFF	Unloc	k						-		1
LoE	LEI	PR	ock		baramet the fun			n not be chan	iged		oFF
		P85	ock								
	LC5					ameter	to YES, rese	t all paramete	ers to		
	102		no / 9E5		default. Hold the , , , , keys for 5 sec, to enter parameter						00
l nl		i				≫, ⊗ k	eys ior 5 sec	, to enter pur	ameter	-	
l nl		i		Hold			eys ior 5 sec	, to enter pur	ameter	_	
%1: Disp	no / 969 layed or	ly for	feedback co	Hold reset ntrol i	the 💽, [ parame nodels.	eter.			ameter	_	
%1: Disp	no / 969 layed or	ly for	feedback co imeters avail	Hold reset ntrol i	the 💽, [ parame nodels.	eter.	e control inp	put.		- 	
%1: Disp %2: Set t	Iayed or	ly for		Hold reset ntrol i	the 💽, [ parame nodels. depend	s on th	e control inp	put.	Output		Monitoring
%1: Disp %2: Set t	no / 969 layed or	ly for		Hold reset ntrol i	the 💽, [ parame nodels.	s on th	e control inp	put.			Monitoring value [/ n]
%1: Disp %2: Set t	Iayed or	ily for v para		Hold reset ntrol i	the 💽, [ parame nodels. depend	s on th	e control inp Input correction	put. Input slope correction	Output slope		value
%1: Disp %2: Set t Type	Iayed or the below	ily for v para	meters avail	Hold reset ntrol i	the 💽, [ parame nodels. depend	s on th	e control inp Input correction	Dut. Input slope correction [5Pn]	Output slope [5 L P]		value
×1: Disp ×2: Set t Type Auto control	no / 955 layed or the below Input Current Voltage	ily for v para	DC4-20mA	Hold reset ntrol i	the 💽, [ parame nodels. depend	s on th y 420	e control inp Input correction [i nb]	Input slope correction [5Pn]	Output slope [5LP]		value
×1: Disp ×2: Set t Type Auto control	no / 955 layed or the below Input Current Voltage	lly for v para	DC4-20mA 1-5VDC	Hold reset	the 💽, [ parame nodels. depend Displa	eter. s on th y 1-5	e control inp Input correction [! nb]	Input slope correction [5Pn]	Output slope [5 L P]		value [/ n]
×1: Disp ×2: Set t Type Auto control	Input Input Current Voltage pulse vo No-volt	lly for w para	DC4-20mA 1-5VDC 5-12VDC	Hold reset	the 💽, [ parame nodels. depend Displa	420 1-5 5 12	e control inp correction [! nb] O X	put. Input slope correction [5Pn] O X	Output slope [5L P]		Value [/ n] The last control input
× 1: Disp × 2: Set t Type Auto control (AUTO)	Input Input Current Voltage pulse vo No-volt	lly for w para	DC4-20mA 1-5VDC 5-12VDC ON/OFF co unication Inside adjus	Hold reset ntrol i able ntact	the 💽, [ parame nodels. depend Displa	420 1-5 5 12 0 n F C o ñ 1 - r	e control inp correction [! nb] O × ×	Input slope correction [5Pn] O X X	Output slope [5L P]		Value [In] The last control input value
X1: Disp X2: Set f Type Auto control (AUTO) Manual	Input Input Current Voltage pulse vo No-volt	lly for w para bltage age comm	DC4-20mA 1-5VDC 5-12VDC ON/OFF co unication Inside adjus Outside adj	Hold reset ntrol i able ntact	the 💽, [ parame nodels. depend Displa	420 1-5 5 12 0 0 F	e control inp correction [! nb] O × ×	Input slope correction [5Pn] O X X	Output slope [5L P]		Value [/ n] The last control input
%1: Disp	Input Input Current Voltage pulse ve No-volt RS485	lly for w para bltage age comm	DC4-20mA 1-5VDC 5-12VDC ON/OFF co unication Inside adjus	Hold reset ntrol i able ntact	the (@) [ parame models. depend Display	420 1-5 5 12 0 n F C o ñ 1 - r	e control inp Input correction [* nb] O × × × ×	Input slope correction [5Pn] × × × ×	Output slope [5L P] O O X		Value [In] The last control input value

○ Parameter 1 group [PR !]

