







## **Model Number**

### UB1000-18GM75A-I-V15

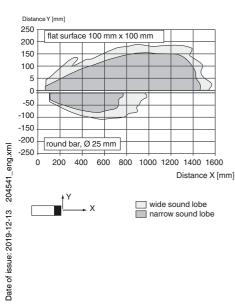
Single head system

### **Features**

- Analog output 4 mA ... 20 mA
- Measuring window adjustable
- Selectable sound lobe width
- **Program input**
- Synchronization options
- **Deactivation option**
- **Temperature compensation**
- Very small unusable area

### **Diagrams**

# Characteristic response curve



# **Technical data**

**General specifications** 70 ... 1000 mm Sensing range Adjustment range 90 ... 1000 mm Dead band 0 ... 70 mm 100 mm x 100 mm Standard target plate Transducer frequency approx. 255 kHz Response delay approx. 125 ms Indicators/operating means

LED yellow solid yellow: object in the evaluation range yellow, flashing: program function, object detected I FD red solid red: Error

**Electrical specifications** 

Operating voltage U<sub>B</sub> 10 ... 30 V DC , ripple 10  $\%_{SS}$ 

No-load supply current I<sub>0</sub> ≤ 45 mA

Input/Output

bi-directional Synchronization 0 level -U<sub>B</sub>...+1 V 1 level: +4 V...+U<sub>B</sub> input impedance: > 12 KOhm

synchronization pulse: ≥ 100 µs, synchronization interpulse

red, flashing: program function, object not detected

period: ≥ 2 ms

Synchronization frequency Common mode operation

Multiplex operation  $\leq$  40 Hz / n, n = number of sensors, n  $\leq$  5

≤ 40 Hz

Input

Input type 1 program input

lower evaluation limit A1: -U<sub>B</sub> ... +1 V, upper evaluation limit

input impedance: > 4.7 k $\Omega$ , pulse duration:  $\geq$  1 s

Output Output type 1 analog output 4 ... 20 mA

Resolution

Deviation of the characteristic curve ± 1 % of full-scale value ± 0.1 % of full-scale value Reneat accuracy

0 ... 300 Ohm Load impedance Temperature influence

± 1.5 % of full-scale value **Ambient conditions** 

Ambient temperature -25 ... 70 °C (-13 ... 158 °F) -40 ... 85 °C (-40 ... 185 °F) Storage temperature

Mechanical specifications

Connection type Connector plug M12 x 1, 5-pin

Degree of protection

Material

brass, nickel-plated Housing

Transducer epoxy resin/hollow glass sphere mixture; polyurethane foam

Mass Compliance with standards and

directives

Standard conformity

Standards EN 60947-5-2:2007+A1:2012

IEC 60947-5-2:2007 + A1:2012 EN 60947-5-7:2003

IEC 60947-5-7:2003

Approvals and certificates

cULus Listed, General Purpose **UL** approval CSA approval cCSAus Listed, General Purpose

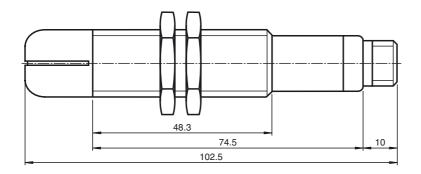
CCC approval

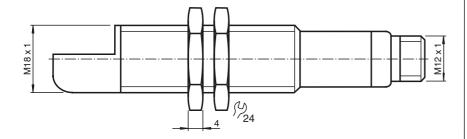
CCC approval / marking not required for products rated ≤36 V

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narrow sound lobe

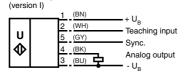
## **Dimensions**





# **Electrical Connection**

### Standard symbol/Connections:



Core colours in accordance with EN 60947-5-2.

## **Pinout**

## **Connector V15**



# **Accessories**

### **UB-PROG2**

Programming unit

### OMH-04

Mounting aid for round steel ø 12 mm or sheet 1.5 mm ... 3 mm

### RF 18

Mounting flange, 18 mm

### BF 18-F

Plastic mounting adapter, 18 mm

### BF 5-30

Universal mounting bracket for cylindrical sensors with a diameter of 5  $\dots$  30  $\mbox{mm}$ 

## UVW90-K18

Ultrasonic -deflector

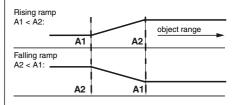
## V15-G-2M-PVC

Female cordset, M12, 5-pin, PVC cable

### M18K-VE

# **Additional Information**

## Programming the analog output mode



### **Synchronisation**

The sensor features a synchronisation input for the suppression of mutual interference. If this input is not used, the sensor will operate using an internally generated clock rate. The synchronisation of multiple sensors can be realised as follows:

### **External synchronisation**

The sensor can be synchronised by the external application of a square wave voltage. A synchronisation pulse at the synchronisation input starts a measuring cycle. The pulse must have a duration greater than 100  $\mu$ s. The measuring cycle starts with the falling edge of a synchronisation pulse. A low level > 1 s or an open synchronisation input will result in the normal operation of the sensor. A high level at the synchronisation input disables the sensor. Two operating modes are available:

- 1. Multiple sensors can be controlled by the same synchronisation signal. The sensors are synchronised.
- 2. The synchronisation pulses are sent cyclically to individual sensors. The sensors operate in multiplex mode.

### Internal synchronisation

The synchronisation connections of up to 5 sensors capable of internal synchronisation are connected to one another. When power is applied, these sensors will operate in multiplex mode.

The response delay increases according to the number of sensors to be synchronised. Synchronisation cannot be performed during TEACH-IN and vice versa. The sensors must be operated in an unsynchronised manner to teach the evaluation limits.

### Note:

If the option for synchronisation is not used, the synchronisation input has to be connected to ground (0V) or the sensor has to be operated via a V1 cable connector (4-pin).

### Adjusting the evaluation limits

The ultrasonic sensor features an analogue output with two teachable evaluation limits. These are set by applying the supply voltage  $-U_B$  or  $+U_B$  to the TEACH-IN input. The supply voltage must be applied to the TEACH-IN input for at least 1 s. LEDs indicate whether the sensor has recognised the target during the TEACH-IN procedure. The lower evaluation limit A1 is taught with  $-U_B$ , A2 with  $+U_B$ .

Two different output functions can be set:

- 1. Analogue value increases with rising distance to object (rising ramp)
- 2. Analogue value falls with rising distance to object (falling ramp)

Evaluation limits may only be specified within the first 5 minutes after Power on. To modify the evaluation limits later, the user may specify the desired values only after a new Power On.

## **TEACH-IN** rising ramp (A2 > A1)

- Position object at lower evaluation limit
- TEACH-IN lower limit A1 with U<sub>B</sub>
- Position object at upper evaluation limit
- TEACH-IN upper limit A2 with + U<sub>B</sub>

# TEACH-IN falling ramp (A1 > A2):

- Position object at lower evaluation limit
- TEACH-IN lower limit A2 with + U<sub>B</sub>
- Position object at upper evaluation limit
- TEACH-IN upper limit A1 with  $U_{\mbox{\footnotesize B}}$

## **Default setting**

A1: unusable area

A2: nominal sensing range

Mode of operation: rising ramp

# **LED Displays**

Displays in dependence on operating mode	Red LED	Yellow LED
TEACH-IN evaluation limit		
Object detected	off	flashes
No object detected	flashes	off
Object uncertain (TEACH-IN invalid)	on	off
Normal mode (evaluation range)	off	on
Fault	on	previous state

# Adjusting the sound cone characteristics:

The ultrasonic sensor enables two different shapes of the sound cone, a wide angle sound cone and a small angle sound cone.

### 1. Small angle sound cone

- · switch off the power supply
- connect the Teach-In input wire to -U<sub>B</sub>
- switch on the power supply
- the red LED flashes once with a pause before the next.
- yellow LED: permanently on: indicates the presence of an object or disturbing object within the sensing range
- disconnect the Teach-In input wire from -U<sub>B</sub> and the changing is saved



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## 2. Wide angle sound cone

- · switch off the power supply
- connect the Teach-In input wire with +UB
- switch on the power supply
- the red LED double-flashes with a long pause before the next.
- yellow LED: permanently on: indicates an object or disturbing object within the sensing range
- disconnect the Teach-In input wire from  $+U_B$  and the changing is saved

