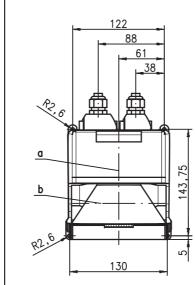
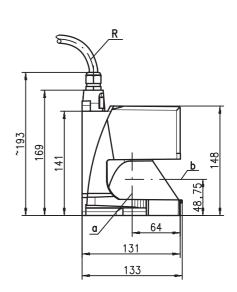
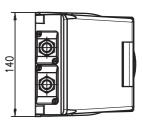
**Optical Distance Sensors** 

### rotoScan ROD 4-3...

### **Dimensioned drawing**



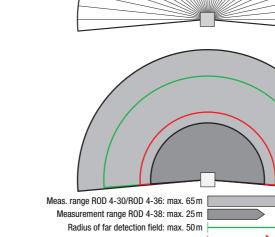




- Zero point for measuring а
- b Scanning plane
- R Smallest bending radius = 50mm

### **Measurement principle**

528 sectors 0.36° each 190° working range Meas. range ROD 4-30/ROD 4-36: max. 65 m Measurement range ROD 4-38: max. 25 m Radius of far detection field: max. 50 m Radius of near detection field: max. 30 m



rotoScan ROD4-3... - 01

24 V DC

The rotoScan ROD 4 is an area scanning • distance sensor for object detection. The light beam is deflected via a rotating mirror and spread across a semicircular area (190°).

0...65m

- Max. radius of detection field 50m
- Measurement range 0 ... 65m
- 7 configurable detection field pairs (near • and far detection fields) for object detection
- Changeover of detection field pairs via • inputs
- Simple device exchange without PC by means of config. connector
- Reference contour for presence/absence . checks of objects
- Independent, simultaneous monitoring of • 4 detection fields
- Interference suppression in the event of • particles in the air
- ROD 4-36 with heating and ROD 4-38 with heating, dust-insensitive version.



## Accessories:

(available separately)

- Mounting systems
- RODsoft configuration software . (free download from www.leuze.de)
- Various connection cables •

Leuze electronic GmbH + Co. KG info@leuze.de • www.leuze.com

reserve the right to make changes • DB ROD 4-3x en.fm

We

## rotoScan ROD 4-3...

### Tables

# **Specifications**

#### **Optical data**

Measurement range Radius of detection field

Angular range Angular resolution Scanning rate Transmitter

#### **Detection fields**

Reflectivity Object size Response time Number of detection field pairs Output Measur. value resolution Repeatability

### **Electrical data**

Voltage supply<sup>1)</sup> Overcurrent protection Current consumption

Power consumption Overvoltage protection

### Mechanical data

Housing Weight Connection type

#### **Environmental data** Ambient temp. (operation/storage)

VDE safety class Protection class Laser class Standards applied 0 ... 65m (ROD 4-38: 0 ... 25m) Ò... 30m near: 0...50m far: max. 190° 0.36 25 scans/s or 40 ms/scan infrared laser diode, laser class 1 (EN 60815-1), wavelength = 905nm,  $P_{max} = 15W$ , pulse duration: 3ns, average output power:  $12\mu W$ 

from min. 1.8% (matte black), ROD 4-38 from 6% (dark grey)  $>20\,mm$  at distance of 4m,  $>100\,mm$  at distance of 15m at least 40ms (corresponds to 1 scan) 7 (selectable via switching inputs) 4 x PNP transistor outputs, 24V/250mA 5mm 10 ... 90% diffuse reflection at operating range of 4m: 15mm

+24VDC +20% / -30% fuse 2A (4A with heating) semi time-lag in the switch cabinet approx. 400mA (use power supply with 2.5A), approx. 2.5A with heating < 60W at 24V including the outputs overvoltage protection with protected limit stop

diecast aluminium, plastic 2.0kg 2 connectors (can be plugged from above, solder connection)

-0°C ... +50°C / -20°C ... +50 C -20°C ... +50°C / -20°C ... +50 C (ROD 4-36, ROD 4-38) Ш IP 65 1 (acc. to EN 60825-1) IEC 60947-5-2

TxD +

TxD -

RxD -

RxD -

GND/SHIELD

Designation

RS select

NC 7-

NC

2-

3-

4 —

5

6

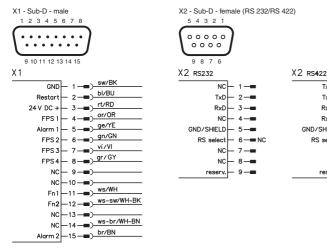
- 8-

9reserv.

Dout No

1) Protective Extra Low Voltage (PELV) - protective extra-low voltage with reliable disconnection. For UL applications: only for use in class 2 circuits according to NEC.

## Electrical connection



## Order guide

	Designation	Fait NU.
	ROD 4-30	501 10238
With heating	ROD 4-36	501 10666
5		301 10000
With heating/dust-insensitive	ROD 4-38	501 10667
-		

# Notices

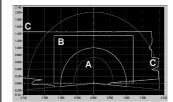
#### "RODsoft" Configuration Software

The configuration software runs under Windows 95/98/ NT/2000/XP and offers the following features:

- Definition of the detection fields
- Configuration of the scanner parameters
- Visualisation of the detection fields and measurement values
- Display of status/diagnostic information
- Support of various languages

There are a variety of options available for defining detection fields. These include e.g.:

- "Teach-In" function
- Numeric and graphical input of the detection fields
- "Edit" function



- Α Near detection field
- в Far detection field
- C Current measurement values
- Approved purpose: The ROD 4 distance sensors are optoelectronic sensors for the optical. contactless measurement of distance to objects.