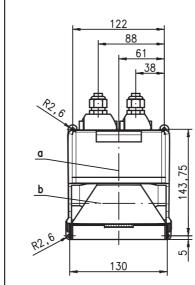
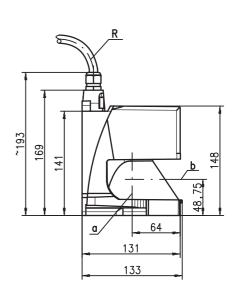
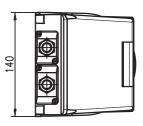
Optical Distance Sensors

rotoScan ROD 4-3...

Dimensioned drawing



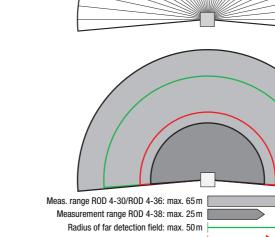




- Zero point for measuring а
- b Scanning plane
- R Smallest bending radius = 50mm

Measurement principle

528 sectors 0.36° each 190° working range Meas. range ROD 4-30/ROD 4-36: max. 65 m Measurement range ROD 4-38: max. 25 m Radius of far detection field: max. 50 m Radius of near detection field: max. 30 m



rotoScan ROD4-3... - 01

24 V DC

The rotoScan ROD 4 is an area scanning • distance sensor for object detection. The light beam is deflected via a rotating mirror and spread across a semicircular area (190°).

0...65m

- Max. radius of detection field 50m
- Measurement range 0 ... 65m
- 7 configurable detection field pairs (near • and far detection fields) for object detection
- Changeover of detection field pairs via • inputs
- Simple device exchange without PC by means of config. connector
- Reference contour for presence/absence . checks of objects
- Independent, simultaneous monitoring of • 4 detection fields
- Interference suppression in the event of • particles in the air
- ROD 4-36 with heating and ROD 4-38 with heating, dust-insensitive version.



Accessories:

(available separately)

- Mounting systems
- RODsoft configuration software . (free download from www.leuze.de)
- Various connection cables •

Leuze electronic GmbH + Co. KG info@leuze.de • www.leuze.com

reserve the right to make changes • DB ROD 4-3x en.fm

We

rotoScan ROD 4-3...

Tables

Specifications

Optical data

Measurement range Radius of detection field

Angular range Angular resolution Scanning rate Transmitter

Detection fields

Reflectivity Object size Response time Number of detection field pairs Output Measur. value resolution Repeatability

Electrical data

Voltage supply¹⁾ Overcurrent protection Current consumption

Power consumption Overvoltage protection

Mechanical data

Housing Weight Connection type

Environmental data Ambient temp. (operation/storage)

VDE safety class Protection class Laser class Standards applied 0 ... 65m (ROD 4-38: 0 ... 25m) Ò... 30m near: 0...50m far: max. 190° 0.36 25 scans/s or 40 ms/scan infrared laser diode, laser class 1 (EN 60815-1), wavelength = 905nm, $P_{max} = 15W$, pulse duration: 3ns, average output power: $12\mu W$

from min. 1.8% (matte black), ROD 4-38 from 6% (dark grey) $>20\,mm$ at distance of 4m, $>100\,mm$ at distance of 15m at least 40ms (corresponds to 1 scan) 7 (selectable via switching inputs) 4 x PNP transistor outputs, 24V/250mA 5mm 10 ... 90% diffuse reflection at operating range of 4m: 15mm

+24VDC +20% / -30% fuse 2A (4A with heating) semi time-lag in the switch cabinet approx. 400mA (use power supply with 2.5A), approx. 2.5A with heating < 60W at 24V including the outputs overvoltage protection with protected limit stop

diecast aluminium, plastic 2.0kg 2 connectors (can be plugged from above, solder connection)

-0°C ... +50°C / -20°C ... +50 C -20°C ... +50°C / -20°C ... +50 C (ROD 4-36, ROD 4-38) Ш IP 65 1 (acc. to EN 60825-1) IEC 60947-5-2

TxD +

TxD -

RxD -

RxD -

GND/SHIELD

Designation

RS select

NC 7-

NC

2-

3-

4 —

5

6

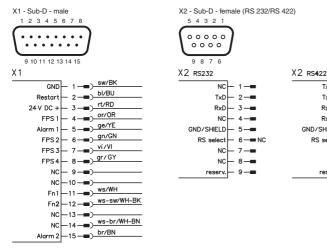
- 8-

9reserv.

Dout No

1) Protective Extra Low Voltage (PELV) - protective extra-low voltage with reliable disconnection. For UL applications: only for use in class 2 circuits according to NEC.

Electrical connection



Order guide

	Designation	Fait NU.
	ROD 4-30	501 10238
With heating	ROD 4-36	501 10666
5		301 10000
With heating/dust-insensitive	ROD 4-38	501 10667
-		

Notices

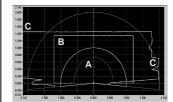
"RODsoft" Configuration Software

The configuration software runs under Windows 95/98/ NT/2000/XP and offers the following features:

- Definition of the detection fields
- Configuration of the scanner parameters
- Visualisation of the detection fields and measurement values
- Display of status/diagnostic information
- Support of various languages

There are a variety of options available for defining detection fields. These include e.g.:

- "Teach-In" function
- Numeric and graphical input of the detection fields
- "Edit" function



- Α Near detection field
- в Far detection field
- C Current measurement values
- Approved purpose: The ROD 4 distance sensors are optoelectronic sensors for the optical. contactless measurement of distance to objects.