#### **Technical data General specifications** Measurement range object thickness (d): 0 ... 30 mm Dead band 0 ... 15 mm Reference distance h 50 ... 60 mm Standard target plate 10 mm x 10 mm Transducer frequency approx. 850 kHz Response delay approx. 12 ms Indicators/operating means solid yellow: object in the evaluation range LED yellow yellow, flashing: program function, object detected LED red solid red: Error red, flashing: program function, object not detected **Electrical specifications** Operating voltage UB 10 ... 30 V DC , ripple 10 $\%_{\rm SS}$ No-load supply current $I_0$ Time delay before availability $t_v$ $\leq$ 30 mA ≤ 200 ms Input CE Input type 1 funtion input 0-level: $-U_B or$ unwired 1-level: $+4 V \dots +U_B$ input impedance: $> 4.7 k\Omega$ Output Model Number Output type 1 analog output 4 ... 20 mA Resolution 0.17 mm UBH60/30-12GM-I-V1-Y266698 Deviation of the characteristic curve ± 1 % of full-scale value Single head system ± 0.5 % of full-scale value Repeat accuracy 0 ... 300 Ohm Load impedance **Features** Ambient conditions Thickness measurement with Ambient temperature -25 ... 70 °C (-13 ... 158 °F) analog output 4 ... 20 mA -40 ... 85 °C (-40 ... 185 °F) Storage temperature Mechanical specifications Extremely narrow projection cone Connector M12 x 1 , 4-pin Connection type Degree of protection IP67 Short response time Material Calibration of the reference Housing brass, nickel-plated epoxy resin/hollow glass sphere mixture; foam polyurethane, cover PBT distance via function input Transducer 25 g Mass Diagrams Compliance with standards and directives Standard conformity Characteristic response curve EN 60947-5-2:2007+A1:2012 Standards IEC 60947-5-2:2007 + A1:2012 Distance Y (mm) EN 60947-5-7:2003 25 IEC 60947-5-7:2003

20 15 10 5 0 -5 -10 -15 -20 -25 40 20 60 Distance X [mm] Approvals and certificates

UL approval CCC approval cULus Listed, Class 2 Power Source CCC approval / marking not required for products rated ≤36 V

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# UBH60/30-12GM-I-V1-Y266698

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## UBH60/30-12GM-I-V1-Y266698

**Additional Information** 

Sensor

Mounting

### Dimensions



# **Electrical Connection**

#### Standard symbol/Connections:



Core colors in accordance with EN 60947-5-2.

#### Pinout



#### Wire colors in accordance with EN 60947-5-2

1	BN	(brown)
2	WH	(white)
3	BU	(blue)
4	BK	(black)



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#### Accessories

UB-PROG2 Programming unit

#### BF 5-30

Universal mounting bracket for cylindrical sensors with a diameter of 5 ... 30 mm

**BF 12** Mounting flange, 12 mm

BF 12-F Mounting flange with dead stop, 12 mm

V1-G-2M-PVC Female cordset, M12, 4-pin, PVC cable V1-W-2M-PUR

Female cordset, M12, 4-pin, PUR cable

#### **Functional description**

This sensor is used to measure the thickness of objects. It teaches itself by independently switching to a reference object. The distance h to this object serves as a reference distance and defines the object thickness 0 mm. This reference distance can be dynamically tracked in order to compensate for external influences. This guarantees a high measurement accuracy of the sensor over the entire temperature range.

#### Automatic teach-in process

Immediately after the supply voltage is connected, the sensor automatically references itself to the reference object and teaches in the distance as the reference distance. The distance h between the sensor surface and the reference object must lie within the valid range for the reference distance (see Technical Data). The sensor then immediately reverts to normal operation.

If no reference object is detected, the red LED flashes (Fault).

#### Normal operation

In normal operation, the sensor outputs a value at the analog output, which is proportional to the thickness of the object. The object thickness 0 mm (measurement to the reference object) is represented in this by the minimum analog value and the largest measurable object thickness (see Technical Data) is represented by the maximum analog value.

#### Manual tracking of the reference distance

A manual tracking of the reference distance can be triggered by means of the functional input.

#### Triggering the manual tracking:

#### (connect functional input to $+U_B$ )

The automatically during the start-up procedure adjusted reference distance can be overwritten during normal operation. Therefore the functional input has to be connected to  $+U_B$ . This causes the current measured distance to be taken as the new reference distance. After this manual replacement of the reference distance the functional input has to be disconnected or connected to - $U_B$ , again.

#### Manual tracking de-activated:

(Functional imput unconnected or connected to  $-U_B$ )

The sensor operates in normal operation mode with the last reference distance adjustment.

#### **Functional input**

The functional input can be used to trigger the manual reference distance tracking (see above).

#### LED indicator

Indication as a function of operating status	red LED	yellow LED
Teach-in control limit:		
No reference object detected or reference	Flashes	Off
object at an incorrect distance		
Normal operation:		
Measurement on object	Off	On
Measurement on reference	Off	Off
Fault	On	Last valid status

#### Installation conditions

If the sensor is installed at places, where the environment temperature can fall below 0 °C, for the sensors fixation, one of the mounting flanges BF 12, BF 12-F or BF 5-30 must be used. In case of direct mounting of the sensor in a through hole, it has to be fixed at the middle of the housing thread.

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