

## **Model Number**

UB2000-F54-I-V15

Single head system

### **Features**

- Analog output 4 mA ... 20 mA
- Measuring window adjustable
- **Program input** .
- Synchronization options •
- **Deactivation option**
- Temperature compensation

## Diagrams

#### Characteristic response curve



# **General specifications** Sensing range Adjustment range Dead band Standard target plate Transducer frequency Response delay Indicators/operating means LED green LED yellow LED red **Electrical specifications** Operating voltage UB No-load supply current I<sub>0</sub> Input/Output Synchronization Synchronization frequency Common mode operation Multiplex operation Input Input type Output Output type Default setting Resolution Deviation of the characteristic curve Repeat accuracy Load impedance Temperature influence Ambient conditions Ambient temperature Storage temperature Mechanical specifications Connection type Degree of protection Material Housing Transducer Mass Compliance with standards and directives Standard conformity Standards

**Technical data** 

#### Approvals and certificates

UL approval	
CSA approval	
CCC approval	

80 ... 2000 mm 100 ... 2000 mm 0 ... 80 mm 100 mm x 100 mm approx. 175 kHz ≤ 150 ms

solid green: monitoring system green flashing: program function solid yellow: object in the evaluation range yellow, flashing: program function, object detected . flashing: normal mode: error Program function: no object detected permanently: Program mode, object uncertain

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 $10 \dots 30 \text{ V DC}$  , ripple  $10 \ \%_{\text{SS}}$ ≤ 55 mA

1 synchronous input 0-level: -U<sub>B</sub>...+1 V 1-level: +4 V...+U<sub>B</sub> input impedance: > 12 KOhm synchronization pulse: 0,1 ... 28 ms

≤ 33 Hz  $\leq$  33 / n Hz, n = number of sensors

1 program input lower evaluation limit A1: -U<sub>B</sub> ... +1 V, upper evaluation limit A2: +4 V ... +U<sub>B</sub> input impedance: > 4.7 k $\Omega$ , pulse duration:  $\geq$  1 s

1 analog output 4 ... 20 mA evaluation limit A1: 100 mm evaluation limit A2: 2000 mm 0.5 mm ± 1 % of full-scale value + 0.1 % of full-scale value 0 ... 300 Ohm ± 1.5 % of full-scale value

-25 ... 70 °C (-13 ... 158 °F) -40 ... 85 °C (-40 ... 185 °F)

Connector M12 x 1 , 5-pin IP65

ABS epoxy resin/hollow glass sphere mixture; polyurethane foam 100 g

EN 60947-5-2:2007 + A1:2012 IEC 60947-5-2:2007 + A1:2012 EN 60947-5-7:2003 IEC 60947-5-7:2003

cULus Listed, General Purpose cCSAus Listed, General Purpose CCC approval / marking not required for products rated ≤36 V

Refer to "General Notes Relating to Pepperl+Fuchs Product Information"

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# Dimensions



Bore hole and countersinking for screws/hexagon M4



# **Electrical Connection**



Core colours in accordance with EN 60947-5-2.

## Pinout



#### Wire colors in accordance with EN 60947-5-2

1	BN WH	(brown) (white)
3	BU	(blue)
4	BK	(black)
5 l	GY	(gray)

# Accessories

**UB-PROG2** Programming unit

V15-G-2M-PVC Female cordset, M12, 5-pin, PVC cable

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# **Additional Information**

# Programming the analog output mode



## Synchronisation

The sensor features a synchronisation input for the suppression of mutual interference. If this input is not used, the sensor will operate using an internally generated clock rate. The synchronisation of multiple sensors can be realised as follows:

External synchronisation:

The sensor can be synchronised by the external application of a square wave voltage. A synchronisation pulse at the synchronisation input starts a measuring cycle. The pulse must have a duration greater than 100  $\mu$ s. The measuring cycle starts with the falling edge of a synchronisation pulse. A low level > 1 s or an open synchronisation input will result in the normal operation of the sensor. A high level at the synchronisation input disables the sensor.

Two operating modes are available:

1. Multiple sensors can be controlled by the same synchronisation signal. The sensors are synchronised.

2. The synchronisation pulses are sent cyclically to individual sensors. The sensors operate in multiplex mode.

## Internal synchronisation:

The synchronisation connections of up to 5 sensors capable of internal synchronisation are connected to one another. When power is applied, these sensors will operate in multiplex mode.

The response delay increases according to the number of sensors to be synchronised.

Synchronisation cannot be performed during TEACH-IN and vice versa. The sensors must be operated in an unsynchronised manner to teach the evaluation limits.

## Note:

If the option for synchronisation is not used, the synchronisation input has to be connected to ground (0V) or the sensor has to be operated via a V1 cable connector (4-pin).

# Adjusting the evaluation range (analogue output)

The ultrasonic sensor has an analogue output with programmable evaluation limits. These are set by applying the supply voltage  $-U_B$  or  $+U_B$  to the TEACH-IN input. The supply voltage must be applied to the TEACH-IN input for at least 1 s. LEDs indicate whether the sensor has recognised the target during the TEACH-IN procedure. The lower evaluation limit A1 is taught with  $-U_B$ , A2 with  $+U_B$ .

Two different output functions can be set:

- 1. Analogue value increases with rising distance to object (rising ramp)
- 2. Analogue value falls with rising distance to object (falling rampe)

## TEACH-IN rising ramp (A1 > A2)

- Position object at lower evaluation limit
- TEACH-IN lower limit A1 with  $\mathrm{U}_\mathrm{B}$
- Position object at upper evaluation limit
- TEACH-IN upper limit A2 with + UB

# TEACH-IN falling ramp (A1 > A):

- Position object at lower evaluation limit
- TEACH-IN lower limit A2 with + U<sub>B</sub>
- Position object at upper evaluation limit
- TEACH-IN upper limit A1 with  $\mathrm{U}_\mathrm{B}$

## LED Displays

Displays in dependence on operating mode	Red LED	Yellow LED	Green LED
TEACH-IN evaluation limit			
Object detected	off	flashes	flashes
No object detected	flashes	off	flashes
Object uncertain (TEACH-IN invalid)	on	off	flashes
Normal mode (evaluation range)	off	on	on
Fault	flashes	previous	off
		state	

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