

CE

Model Number

ML100-8-HW-350-RT/95/103

Triangulation sensor (BGE) with 4-pin, M8 x 1 connector

Features

- User-friendliest photoelectric sensor • series for standard applications
- Miniature design ٠
- Background evaluation uses back-• ground as reference for detection of difficult targets
- Simplest alignment and commissio-٠ ning thanks to ultrabright transmitter LED
- Clear and functional display concept for the operating modes
- Full metal thread mounting ٠

Product information

The ML100 series is characterized by its miniature housing with integral, all-metal threaded bushings. All versions are equipped with a visible red transmitter LED. This greatly simplifies installation and commissioning. The switching states are easily visible from all directions thanks to the highly visible LEDs.



Electrical connection









Indicators/operating means

²₁ 3



1	Light-Dark-switching	
2	2 Detection range adjuster	
3	Signal display	yellow
4	Operating display	green

Refer to "General Notes Relating to Pepperl+Fuchs Product Information" USA: +1 330 486 0001 fa-info@us.pepperl-fuchs.com

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Technical data			• • • • • • • • • • •
lechnical data			Accessories
General specifications			OMH-ML100-03 Mounting aid for rou sheet 1.5 mm 3 m
Detection range		5 350 mm	
Adjustment range		30 350 mm	
Light source		LED	
Light type		modulated visible red light	OMH-ML100-04
Diameter of the light spot		approx. 20 mm at a distance of 350 mm	Mounting aid for ML bracket
Angle of divergence		approx. 4 °	
Optical face		frontal	
Ambient light limit		EN 60947-5-2:2007+A1:2012	OMH-ML100-05
Functional safety related para	meters		Mounting aid for ML
MTTF _d		860 a	bracket
Mission Time (T _M)		20 a	•••••
Diagnostic Coverage (DC)		0 %	OMH-F10-ML100
Indicators/operating means			Mounting aid for ML
Operation indicator		LED green: power on	OMH-10
Function indicator		LED yellow ON: sensor detects background	
Control elements		Sensing range adjuster	Mounting aid
Control elements		Light-on/dark-on changeover switch	V31-GM-2M-PUR
Electrical specifications			Female cordset, M8
Operating voltage	UB	10 30 V DC	
Ripple		max. 10 %	V31-WM-2M-PUR
No-load supply current	I ₀	< 20 mA	Female cordset, M8
Output			
Switching type		The switching type of the sensor is adjustable. The default set- ting is: light on	OMH-ML100-S1 Mounting bracket
Signal output		1 PNP output, short-circuit protected, reverse polarity protected, open collector	OMH-ML100-08
Switching voltage		max. 30 V DC	Mounting aid for ML
Switching current		max. 100 mA , resistive load	Other suitable second
Voltage drop	U _d	≤ 1.5 V DC	Other suitable access
Switching frequency	f	500 Hz	www.pepperl-fuchs.co
Response time		1 ms	
Ambient conditions			
Ambient temperature		-30 60 °C (-22 140 °F)	
Storage temperature		-40 70 °C (-40 158 °F)	
Mechanical specifications			
Degree of protection		IP67	
Connection		connector M8 x 1 , 4-pin	
Material			
Housing		PC (Polycarbonate)	
Optical face		РММА	
Mass		approx. 10 g	
Tightening torque, fastening scr		0.6 Nm	
Compliance with standards an ves	d direct	j.	
Directive conformity			
EMC Directive 2004/108/EC		EN 60947-5-2:2007+A1:2012	
Standard conformity			
Standards		UL 60947-5-2	
Approvals and certificates			

Approvals and certificates UL approval CCC approval

with a limited voltage output with (maybe integrated) fuse (max. 3.3 A according UL248), Type 1 enclosure CCC approval / marking not required for products rated ≤36 V

cULus Listed, Class 2 Power Source or listed Power Supply

und steel ø 12 mm or mm

L100 series, Mounting

L100 series, Mounting

L100 series

8, 4-pin, PUR cable

8, 4-pin, PUR cable

IL100 series, Snap-in

ssories can be found at com

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Curves/Diagrams



Notes

- 1. Set up the sensor to the background object.
- 2. Rotate the detection range adjuster clockwise until the yellow LED turns ON.
- Continue to rotate the detection range adjuster clockwise until the yellow LED turns OFF. З.
- 4. Now counter-clockwise rotate the detection range adjuster just until the yellow LED turns ON again.
- Preferably the background should be light or white.

Object should move transversely to the sensor.

The background should not vary in height.

