



Vision Sensor

PHA500-F200-B17-V1D



- Detects the position of an index hole
- Large capture range
- High operating range
- Integrated contrast compensation
- Compact design
- PROFINET interface
- Integrated illumination

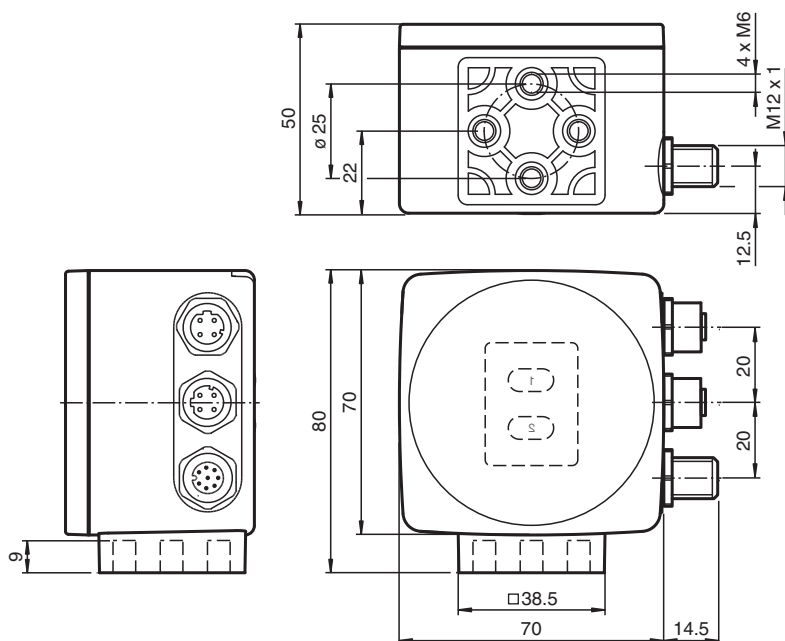
Precision positioning on hole in the 70 mm x 70 mm housing



Function

The sensor has been developed for the precision positioning of high-bay racking operating equipment. It detects circular holes in the racking structure and their positional deviation from the nominal position. The sensor operates in two dimensions.

Dimensions



Technical Data

General specifications

Light type	Integrated LED lightning (infrared)
Object size	Hole diameter 13 mm
Response delay	100 ms
Read distance	500 mm

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Refer to "General Notes Relating to Pepperl+Fuchs Product Information".

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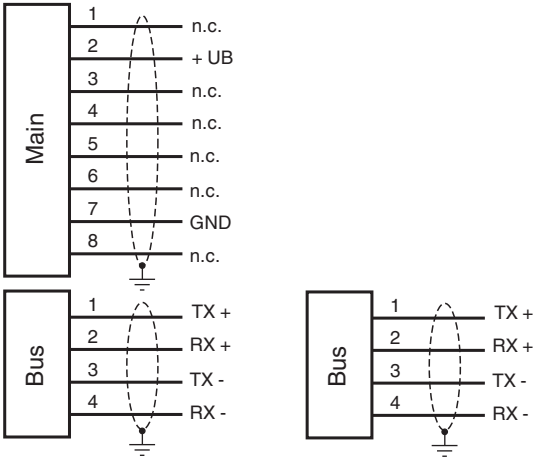
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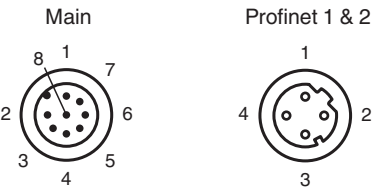
Technical Data

Depth of focus	± 50 mm	
Capture range		max. 90 mm x 90 mm
Nominal ratings		
Camera		
Type	CMOS , Global shutter	
Number of pixels		752 x 480 pixels
Gray scale	256	
Functional safety related parameters		
MTTF _d		20 a
Mission Time (T _M)		10 a
Diagnostic Coverage (DC)	0 %	
Indicators/operating means		
Operation indicator	LED green: Ready for operation	
Function indicator		7 LEDs (communication, alignment aid, status information)
Control elements	Button for parameterization	
Electrical specifications		
Operating voltage	U _B	24 V DC +/- 15 %, PELV
No-load supply current	I ₀	max. 400 mA
Power consumption	P ₀	6 W
Interface		
Interface type	100 BASE-TX PROFINET	
Protocol		PROFINET IO Real-Time (RT) Conformance class A
Transfer rate	100 MBit/s	
Standard conformity		
Noise immunity	EN 61000-6-2:2005	
Approvals and certificates		
UL approval	cULus Listed, General Purpose, Class 2 Power Source	
CCC approval		CCC approval / marking not required for products rated ≤36 V
Approvals	CE	
Ambient conditions		
Operating temperature	0 ... 60 °C (32 ... 140 °F) , -20 ... 60 °C (-4 ... 140 °F) (noncondensing; prevent icing on the lens!)	
Storage temperature		-30 ... 85 °C (-22 ... 185 °F)
Relative humidity	90 % , noncondensing	
Mechanical specifications		
Degree of protection	IP67	
Material		
Housing	PC/ABS	
Optical face		Plastic pane
Installation	4 x M6 threading	
Mass		approx. 200 g

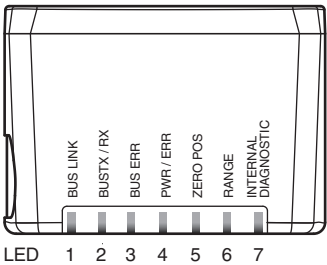
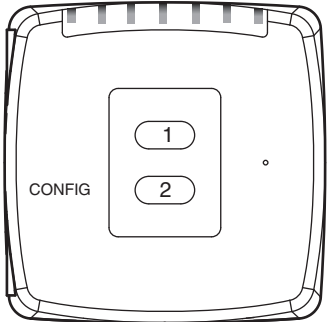
Connection



Connection Assignment

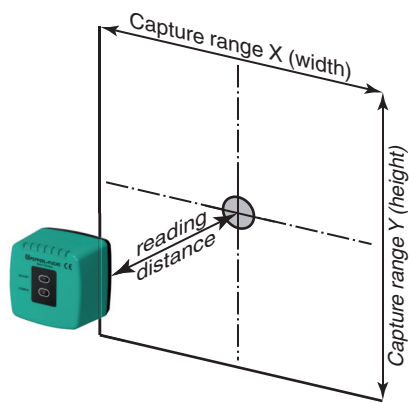


Assembly










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Characteristic Curve



Accessories

	V19-G-5M-PUR-ABG	Female cordset, M12, 8-pin, shielded, PUR cable
	V1SD-G-2M-PUR-ABG-V1SD-G	Ethernet bus cable, M12 to M12, PUR cable 4-pin, CAT5e
	V1SD-G-5M-PUR-ABG-V1SD-G	Ethernet bus cable, M12 to M12, PUR cable 4-pin, CAT5e
	PCV-MB1	Mounting bracket for PCV* read head
	PCV-SC12A	Grounding clip for PCV system
	PCV-SC12	Grounding clip for PCV system
	V19-G-2M-PUR-ABG	Female cordset, M12, 8-pin, shielded, PUR cable

Additional Information

General

The PHA... Vision Sensor has been developed for the rack fine positioning of stock feeders. This device detects circular holes in the rack structure and determines the position deviation of these holes in relation to the target position. The Vision Sensor operates in two dimensions.

Mounting and Commissioning

Mount the PHA... Vision Sensor in such a way that the optical surface of the device captures the optimum distance to the carrier/hole (see "Technical Data"). The stability of the Vision Sensor mounting and the manner in which the vehicle is guided must ensure that the device is not operated outside of its depth of focus range.

All Vision Sensors can be adapted to optimally meet specific requirements by means of parameterization.

Indicators and Controls

The PHA... Vision Sensor is equipped with seven indicator LEDs for carrying out visual function checks and rapid diagnostics. The read head is equipped with two buttons at the back for activating the parameterization mode.

LEDs

LED	Color	Labeling	Meaning
1	yellow	BUS LINK	PROFINET communication active
2	yellow	BUS TX / RX	Data transfer
3	red	BUS ERR	PROFINET communication error
4	green/red	PWR/ERR	Fault with power supply/general error
5	yellow	ZERO POS	Zero position reached
6	yellow	RANGE	Within detection/capture range
7	red/green/yellow	INTERNAL DIAGNOSTIC	Internal diagnostics

External Parameterization

In order to parameterize the device externally, the parameterization code is required in the form of a data matrix containing the desired parameters. Data matrix code cards detailing the step-by-step process for externally parameterizing the device are printed in the operating instructions for the Vision Sensor.

- The Vision Sensor is switched over from normal operation to parameterization mode using button 2 on the back of the device. To switch the device over, button 2 must be pressed and held for more than two seconds. LED5 then flashes.
Note: Parameterization mode is exited automatically if the device is inactive for one minute. In this case, the Vision Sensor reverts to normal mode and operates without the settings having been changed.
- Place the parameterization code in the field of vision of the camera module. After the parameterization code is detected, the green LED4 lights up for one second. In the event of an invalid parameterization code, LED4 lights up red for two seconds.
- Briefly pressing button 2 will end parameterization mode. Unsaved changes will be lost.

Accessories

Other suitable accessories can be found at www.pepperl-fuchs.com