





Model Number

UBR400-F77-E2-V31

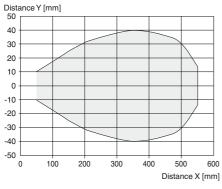
Reflex ultrasonic sensor

Features

- Miniature design
- Program input
- Degree of protection IP67
- Switching status indicator, yellow LED

Diagrams

Characteristic response curve





Technical data

General specifications	
Sensing range	0 400 mm
Adjustment range	53 400 mm
Standard target plate	20 mm x 20 mm
Transducer frequency	approx. 300 kHz

Nominal ratings
Time delay before availability $t_v \le 150 \text{ ms}$

Limit data

Permissible cable length max. 300 m

Indicators/operating means

LED yellow switching state and flashing: Teach-In

Electrical specificationsRated operating voltage U_e

Rated operating voltage $\rm U_e$ 24 V DC Operating voltage $\rm U_B$ 20 ... 30 V DC , ripple 10 $\rm \%_{SS}$; 12 ... 20 V DC sensitivity

reduced to 90 %

No-load supply current $I_0 \le 20 \text{ mA}$

Input type 1 program input

Level low level : 0 ... 0.7 V (Teach-In active) high level : U_B or open input (Teach-In inactive)

Input impedance $16 \text{ k}\Omega$

Pulse length ≥ 3 s

Output

Input

Output type 1 switch output PNP, NO
Rated operating current I_e 200 mA , short-circuit/overload protected

 $\begin{array}{lll} \mbox{Voltage drop U}_d & \leq 2 \ \mbox{V} \\ \mbox{Switch-on delay t}_{on} & \leq 75 \ \mbox{ms} \\ \mbox{Switching frequency f} & 5 \ \mbox{Hz} \\ \mbox{Off-state current I}_r & \leq 0.01 \ \mbox{mA} \\ \mbox{Temperature influence} & + 0.17 \ \% \mbox{K} \\ \end{array}$

Temperature influence
Ambient conditions

 $\begin{array}{lll} \mbox{Ambient temperature} & -25 \dots 70 \mbox{ °C (-}13 \dots 158 \mbox{ °F)} \\ \mbox{Storage temperature} & -40 \dots 85 \mbox{ °C (-}40 \dots 185 \mbox{ °F)} \\ \mbox{Shock resistance} & 30 \mbox{ g , 11 ms period} \\ \end{array}$

Vibration resistance 10 ... 55 Hz , Amplitude ± 1 mm

Mechanical specifications

Connection type M8 x 1 connector , 4-pin

Degree of protection IP67

Material

Housing Polycarbonate
Transducer epoxy resin/hollow glass sphere mixture; polyurethane foam

 Installation position
 any position

 Mass
 10 g

 Tightening torque, fastening screws
 max. 0.2 Nm

Compliance with standards and

directives

Standard conformity

Standards EN 60947-5-2:2007+A1:2012

IEC 60947-5-2:2007 + A1:2012

Approvals and certificates

UL approval cULus Listed, General Purpose

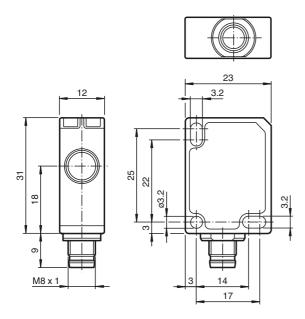
CCC approval / marking not required for products rated ≤36 V

Safety Note



The use of this device in applications, where the safety of persons depends from the devices function, is not allowed!

Dimensions



Description of Sensor Function

The ultrasonic sensor works like a retroreflective sensor. It transmits ultrasonic packages in quick succession and responds to their reflection off a reference object at a defined distance. The distance T to the reference object can be taught in. The sensor has a switch output. This output switches if the reference object is not detected, which happens when another object is located between the sensor and the reference object. The limit of the switching range is derived as follows: T - 5 %.

Notes

- The distance T of the reference object must not be changed during operation. If the distance T changes, it will have to be taught-in again.
- The reference object must not be removed during operation.

Teach-In the Distance to the Reference Object

Proceed as follows to teach in the distance T to the reference object:

- 1. Connect the sensor and turn on the operating voltage.
- Place the reference object at the required distance.
- 3. Connect the teach-in input (ET) to -UB. This can be done using the pushbutton or the con-
 - The LED will start flashing after 3 seconds to indicate that the sensor is ready to start the teach-in process ^(*).
- 4. Disconnect the teach-in input (ET) with -U_B. The distance T to the reference object has now been taught in (*)
- If no object is detected within the sensing range of the sensor, the sensor will start flashing at a faster rate. The switching point remains unchanged.

Switching characteristics and display LED

Sensing range			Output	LED	
Adjustment range					
	Switching area	5%	Reference		
		of	object	-U _B	Off
	•	Т	(position T)	+U _B	On
				+U _B	On

= Object position

Mounting instruction

If the sensor is operated at temperatures below 0 °C, use the supplied distance plate. Only use the two rearmost mounting holes (located opposite to the transducer) for mounting the sensor.

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