# Reflex ultrasonic sensor



# CE

## **Model Number**

# UBR400-F77-E3-V31

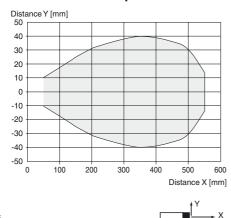
Reflex ultrasonic sensor

## **Features**

- Miniature design
- **Program input** •
- **Degree of protection IP67** •
- Switching status indicator, yellow LED

## Diagrams

## Characteristic response curve



Technical data
General specifications
Sensing range
Adjustment range
Standard target plate
Transducer frequency
Nominal ratings
Time delay before availability t <sub>v</sub>
Limit data
Permissible cable length
Indicators/operating means
LED yellow
Electrical specifications
Rated operating voltage $U_e$
Operating voltage U <sub>B</sub>
No-load supply current I <sub>0</sub>
Input
Input type
Level
Input impedance
Pulse length
Output
Output type
Rated operating current Ie
Voltage drop U <sub>d</sub>
Switch-on delay t <sub>on</sub>
Switching frequency f
Off-state current I <sub>r</sub>
Temperature influence
Ambient conditions
Ambient temperature
Storage temperature
Shock resistance
Vibration resistance
Mechanical specifications
Connection type
Degree of protection
Material
Housing
Transducer
Installation position
Mass
Tightening torque, fastening screws
Compliance with standards and directives
Standard conformity
Standards
Approvals and certificates
UL approval
CCC approval

53 ... 400 mm 20 mm x 20 mm approx. 300 kHz ≤ 150 ms max. 300 m switching state and flashing: Teach-In 24 V DC 20 ... 30 V DC , ripple 10  $\%_{SS}$  ; 12 ... 20 V DC sensitivity reduced to 90 %  $\leq$  20 mA 1 program input low level : 0 ... 0.7 V (Teach-In active) high level : UB or open input (Teach-In inactive)  $16 k\Omega$ ≥3 s 1 switch output PNP , NC contact 200 mA , short-circuit/overload protected  $\leq$  2 V ≤ 75 ms 5 Hz ≤ 0.01 mA + 0.17 %/K -25 ... 70 °C (-13 ... 158 °F) -40 ... 85 °C (-40 ... 185 °F) 30 g , 11 ms period 10 ... 55 Hz , Amplitude ± 1 mm M8 x 1 connector , 4-pin IP67 Polycarbonate epoxy resin/hollow glass sphere mixture; polyurethane foam any position 10 g

0...400 mm

EN 60947-5-2:2007+A1:2012 IEC 60947-5-2:2007 + A1:2012

max. 0.2 Nm

cULus Listed, General Purpose CCC approval / marking not required for products rated ≤36 V

#### Safety Note



The use of this device in applications, where the safety of persons depends from the devices function, is not allowed!

Refer to "General Notes Relating to Pepperl+Fuchs Product Information"

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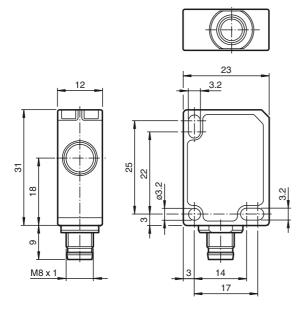
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## Dimensions



## **Description of Sensor Function**

The ultrasonic sensor works like a retroreflective sensor. It transmits ultrasonic packages in quick succession and responds to their reflection off a reference object at a defined distance. The distance T to the reference object can be taught in. The sensor has a switch output. This output switches if the reference object is not detected, which happens when another object is located between the sensor and the reference object. The limit of the switching range is derived as follows: T - 5 %.

#### Notes

- The distance T of the reference object must not be changed during operation. If the distance
- T changes, it will have to be taught-in again. - The reference object must not be removed during operation.

#### Teach-In the Distance to the Reference Object

Proceed as follows to teach in the distance T to the reference object:

- 1. Connect the sensor and turn on the operating voltage.
- 2. Place the reference object at the required distance.
- 3. Connect the teach-in input (ET) to -U<sub>B</sub>. This can be done using the pushbutton or the controller.
- The LED will start flashing after 3 seconds to indicate that the sensor is ready to start the teach-in process <sup>(\*)</sup>.
- 4. Disconnect the teach-in input (ET) with -U<sub>B</sub>. The distance T to the reference object has now been taught in (<sup> $^{(*)}$ </sup>.
- (\*) If no object is detected within the sensing range of the sensor, the sensor will start flashing at a faster rate. The switching point remains unchanged.

#### Switching characteristics and display LED

Sensing range				Output	LED
	Adjustment range				
	Switching area	5%	Reference		
		of	object	+U <sub>B</sub>	On
	•	Т	(position T)	-U <sub>B</sub>	Off
				-U <sub>B</sub>	Off

#### Object position

#### **Mounting instruction**

If the sensor is operated at temperatures below 0 °C, use the supplied distance plate. Only use the two rearmost mounting holes (located opposite to the transducer) for mounting the sensor.

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