

Laser range sensor

Operation manual



CE

PDB series

Precautions

• Please do not use in the following environment

- Oirect sunlight
- ◎ Places with high humidity or easy condensation
- Places containing corrosive gases O Places subject to severe vibration or shock
- Connection and installation
- O Do not use the sensor in an unstable state immediately after the power is turned on, (recommended to test after 30 minutes of power on to achieve desired accuracy)
- \odot Be sure to carry out wiring with the power off. If a wrong wiring occurs, it will cause a malfunction
- \odot Please make sure that the power supply voltage is within the rated value before powering on
- ◎ Please use rated load
- ◎ The RS485 signal line cannot be short-circuited with the power supply, otherwise it may cause product failure or damage the product
- O When installing the sensor, do not subject the sensor to severe external forces(such as hammering, etc), as this may damage the sensor performance
- \odot Do not bend the lead out of the cable with excessive force, and avoid applying pressure such as pulling Cleaning
- ◎ Thinner will corrode the surface of the filter, it is best to avoid using it

 \odot If there is dust on the surface, please wipe it gently with a dry dust-free cloth

Safety Warning

- Do not use in an environment with flammable, explosive or corrosive gases
- The RS485 communication line should not be too long
- Do not disassemble, repair or modify this product without authorization
- This product is dangerous, please do not look directly at the laser or observe the optical system through the lens

Scrap Treatment

• When the product is scrapped, please dispose of it as industrial waste

Laser description



• This sensor series are Class 3 laser products, please do not look directly at the laser or observe it through the laser.Warning labels are affixed to this series, please use them according to label instruction

Accessory Dimensions(Mounting bracket ZJP-15)



Prod	ucts series	Laser distance measuring sensor
	RS-485	PDB-CM8DGR
Model	420mA	PDB-CM8TGI
	010V	PDB-CM8TGU
Measur	ingrange	0.28m®
Measur	ngaccuracy	±1%F.S.®
Repeat	ed stability	±1%F.S.®
Supply	voltage	RS-485:1030VDC;420mA/010V:1224VDC
Consun	nption power	≤700mW
Load cu	rrent	50mA
Voltage	drop	<2.5V
Light so	urce type	Infrared laser(850nm);Laser level:class 3R
Functio	nal principle	TOF
Average	optical power	20mW
Pulse d	uration	50ns
Pulse fr	equency	10MHZ
Detection frequency		100HZ
Light spot size		RS-485:90*90mm(At 5m);420mA/010V:90*90mm(At 5m)
Dimens	ion	65mm*51mm*23mm
Resolut	ion	lmm
Output	1	Digital value:RS-485(Support ModBus protocol);Analog:420mA(Load resistance<300Ω), Analog:010V(Load resistance>5K)
Output	2	Switch value:PUSH-PULL/NPN/PNP,NO/NC Settable
Distanc	e setting	RS-485:Keypress/RS-485 setting;420mA/010V:Keypress setting
Indicate)r	Power indicator: Green LED;Action indicator: Yellow LED, Yellow LED
Return	difference	3cm below 2m,≤2% above 2m
Protect	on circuit	Short circuit, reverse polarity
Built-in	function	Button to lock; button to unlock; action point setting;Output setting; single point teach; Window teach mode setting; factory date reset;Slave address&Port rate setting[only for RS-485]
Service	environment	Operating temperature:-10+50°C
Anti am	bientlight	Incandescent light:<20,000lux
Protect	ion degree	IP67
Materia	l	Housing:ABS;Lens cover:PMMA
Vibratio	n resistant	1055Hz Double amplitude 1mm,2hrs each for X,Y,Z direction
Impulse	withsand	500m/s ² (About 50G),3 times each for X,Y,Z direction
Connec	tion way	RS-485:2m 5pins PVC cable;420mA:2m 4pins PVC cable;010V:2m 4pins PVC cable
Accesso	ry	Screw (M4×35mm) ×2, Nut×2, Washer×2, Mounting bracket, Operation manual
Pomark-	1)Standard test ob	iact-00% white card

Panel introduction



1.Buttor

Used to set the unlock, switch output logic of the sensor, operating point, data filtering, analog, reset.

Т	Toggle buttom	Switch buttom
S	Set buttom	Set buttom

2.Button Setting function

Function list
Action point single point teaching TEACH A
Operation point window teaching TEACH A, TEACH B
Output logic: NO/NC selection
Output status out:NPN/PNP/PUSH-PULL(PP)selection
Filter level Aver: FAST / MEDIUM / SLOW selection
Analog mapping 4mA
Analog mapping 20mA
Reset
Slave address :0x80-0xF4 (only for RS-485)
Port rate: 115200/57600/38400/19200/9600 (only for RS-485)

3.Indicator

Used as power indication, sensing indication, alarm indication, setting indication

Product name	Color	Always on/off	Flashing	
LP	Green	Power indication	—	
L1	Yellow	Consideration		
L2	Yellow	Sensing indication		

India

dicator status description					
Indicator information	Indicator status	Status information			
Action point is sensed	L1-LED L2-LED On On	L1 and L2 are on at the same time			
Action point is not sensed	L1-LED L2-LED Off Off	L1 and L2 are off at the same time			
Switch output overload	L1-LED L2-LED 6.25Hz 6.25Hz	1 and L2 flash asynchronously at a frequency of 6.25Hz			





Instructions

Self-lock and Unlock

1.Unlock:When the key is in the self-locking state, long press the S key for 4-6S. When the screen displays UN LOCK, you can press the key.

- 2.Self-lock:If the button is not pressed within 10 minutes of power-on, it locks itself.After pressing the button to LOCK itself, the screen displays LOCK.The corresponding setting operation cannot be performed.
- PDB-CM**485 Output series





PDB-CM**Analog voltage



PDB-CM**Analog current

Perform the following operations in the unlocked state:



(Short press to cycle through pages)

Wiring diagram



Remark: The sensors are equipped with shielded cables,NPN/PNP is the switch output. RS-485 output:The black and white lines A and B must not be reversed and A and B cannot be short-circuited with the power line " + 、-" Analog output: The gray line Ia cannot be short-circuited with the power line " + , -", and

there is a small shielded wire in the gray line.

Function Description

• Action point single point teaching TEACH A

Within the sensing range,select the first distance value as the operating point and fix the product and the target. When entering the "Teach A" mode, long press the S key to start teaching. For the operation of analog output or 485 output, please refer to "Operation manual". After teaching at specified position,output ON from the position to the near end of the detection range. Actual operating point: Set value * 101%;Actual exit point:Less than set value * 102%.



• Operation point window teaching TEACH A, TEACH B

Within the sensing range, select the first distance value as the operating point and fix the product and the target. Enter the "Teach A" mode and then long press the S key to start teaching After success release the key to automatically

The reach A more and then long press the S key to start teaching, and the second at the key to automatically return to the initial state of the previous level to complete the teaching of the first action point. Then enter the "Teach B" mode and then long press the S key to start teaching. After success, release the key to automatically return to the initial state of the previous level to complete the second

Action point teaching. After success, release the key to automatically return to the initial state of the previous level to complete the second action point teaching. After success, release the key to automatically return to the initial state of the previous level. For the operation of analog output or 485 output, please refer to "Operation manual". If you want to return to single-point teaching after completing window teaching only need to operate "single point teaching", the product will automatically clear the last window teaching value. Actual operating point: Set value * 101%; Actual exit pointLess than set value * 102%.

After teaching at the specified 2 positions the output is ON within the range between 2 positions.

Far sensing point Near sensing point



Analog mapping: 4mA, 20mA

Within the sensing range, after selecting the "current" mode, enter "4mA" or "20mA, select the first distance value as the 4mA mapping point(or 20mA mapping point), and fix the sensor and target. The position of 4mA and 20mA(A,B) points within the effective range can be arbitrarily set, And the distance between (a, b) points is greater than 5% of the current distance, the setting is successful. Otherwise, the setting will fail. The default(A,B)is(4mA,20mA). For the energiting of apple or uptual plane for for the "nearestine mapping" will fail. The default(A,B)is(4mA,20mA). For the operation of analog output.please refer to "Operation manual"





Data transmission (only for RS485)

◆Baud rate:115200(default) ◆Parity check:None Data bits:8

♦Slave default address:0x80 ♦Stop bit:1

Note: The default address is 0x80. Different slave addresses or different baud rates will have different redundancy checks.

1.Master station request message format(Command to read distance information)

	Slave address	Function code	Data start address Data volume (Unit: words)		Redundancy check CRC16-2					
	80	03	9C	7D	MSB:00	LSB:01	LSB:24	MSB:53		
Slave station response message format:										
	Slave address	Function code	Bytes		Data Redundancy		y check CRC16-2			
					-		-	-		

The host computer communicates through RS485,and the sensor data read out needs to be calculated by the following method to obtain actual measured value.

(1)Convert the fourth and fifth bytes in the reply packet from the slave station into decimal. The unit is mm. (2)When the distance is less than 150mm, it is a blind area, and the actual measured value =150; When the distance is greater than 11000mm, the measured range is exceeded, and the actual measured value =11000; For example:The master request message:80 03 9C 7D 00 01 24 53

Actual distance value=2465.

Return: If the setting is successful, the original instruction will be returned; If it fails, an error instruction will be returned

2. The master request message format(The address broadcast call command):

Slave address	Function code	Address where	data is stored	tored Data volume (Unit: words)		Redundancy check CRC16-2				
00	06	9C	7E	00	81	06	33			
The address broadcast call command is used when the address originally set by the sensor is unclear Modify any										

For example: The address originally set by the sensor is unknown, and you want to set the address to 0x81 Then send instructions via RS485 bus:00 06 9C 7E 00 81 06 33 The address originally set by the sensor is unknown, and you want to set the address to 0x82

eturn:There is no return no matter the setting is sucessfully or fails. .Master station request message format(Modified address command):											
Slave address	Function code	Address where data is stored		Mo	Modify value		Redundancy check CRC16-2				
80	06	9C	7E	0	0	85	LSB:18	MSB:30			
ave station response message format:											
Slave address	Function code	Address where	e data is stored	Mo	Modify value		Redundancy check CRC16-2				
80	06	9C	7E	0	0	85	LSB:18	MSB:30			
he modificatio	n is invalid if the	modified add	ress is out of ra	ange.R	etur	n error	instruction:				
Slave address	Function code	Error code	Redundancy cheo		RC1	.6-2					
80	06	02	LSB	MS	в						

The address modification instruction is used to modify any current address value to the required value when the address originally set by the sensor is known. Modify any current address value to the required value through. Address modification range:0x80-0xF4. The effective range of the address setting is 0x80 ~ 0xF4, and the modification of address takes effect after the power is turned on again. For example: The address originally set by the sensor is known, and you want to set the address to 0x81

Then send instructions via RS485 bus:80 06 9C 7E 00 81 19 F3 The address originally set by the sensor is known, and you want to set the address to 0x82 Then send instructions via RS485 bus:81 06 9C 7E 00 82 58 23

Return: If the setting is successful, the original instruction will be returned; If it fails, an error instruction will be returned. For example: Send instructions: 80 06 9C 74 00 06 79 33 Return: 80 86 03 52 49

4.Master station request message format(Modify the baud rate):

Slave address	Function code	Address where	Modify value		Redundancy check CRC16-2						
80	06	9C	7F	MSB:00	LSB:02	LSB:09	MSB:92				
MSB defaults to 00;The LSB bit of the modified value:Baud rate setting,as follows:											
1,200 57600 38400 19200 9600											
01	02	03	04		05						
After setting suc	cessfully,slave st	ation response	message forma	t:							
Slave address	Function code	Address where	data is stored	Modif	y value	Redundancy check CRC16-2					
80	06	9C	7F	MSB	LSB	LSB	MSB				
If it is not within	this range,this o	peration is inval	id.The return o	peration e	error com	mand:					

Slave address Function code Error code Redundancy check CRC16-2 86 02 LSB MSB 80

The baud rate modification command is used when the baud rate originally set by the sensor is known.

Modify any current baud rate value to the required value through the baud rate modification instruction. Address modification range:115200、57600、38400、19200、9600(Level 5) .The default baud rate of the slave is 0x01(115200).The effective range of the baud rate setting is 0x01~0x05 For example: The baud rate originally set by the sensor is known to be 115200, at this time, you want to set the baud

rate to 57600. Then send instructions via RS485 bus:80 06 9C 7F 00 02 09 92

The baud rate originally set by the sensor is known to be 115200,at this time,you want to set the baud rate to 9600 Then send instructions via RS485 bus:80 06 9C 7F 00 05 48 50

Return: If the setting is successful, the original instruction will be returned; If it fails, an error instruction will be returned.

5.Master station	n request messa	ge format(Swite	ching logic setti	ng):			
Slave address	Function code	Address where	data is stored	Modify	value	Redundancy ch	eck CRC16-2
80	06	9C	74	MSB:00	LSB:00	LSB:F9	MSB:91
After setting su	ccessfully,slave	station respons	e message form	nat:			
Slave address	Function code	Address where	data is stored	Modify	value	Redundancy ch	eck CRC16-2
80	06	9C	74	MSB:00	LSB:00	LSB:F9	MSB:91
Modification ra For example:Th Th Th Th Th Th Return:If the se	nge: NPN,PNP,P he sensor now wa hen send comma he sensor now wa hen send comma he sensor now wa he sensor now wa hen send comma titing is successfu	UP(three kinds) ants to set the s ands via RS485 l ants to set the s ands via RS485 l ants to set the s ands via RS485 l ants to set the s ands via RS485 l). switching value bus:80 06 9C 74 switching value bus:80 06 9C 74 switching value bus:80 06 9C 74 nstruction will b	to NPN 00 00 F9 9 to PNP 00 01 38 5 to PUP 00 02 78 5 pe returned	1 1 D d;If it fails	an error instrue,	ction will be ret
6.Master statio	n request messa	ge format(Swite	ch state setting)	: Modify	value	Pedundancy ch	back CPC16-2
80	06	90	73	MSB-00	I SB-00	I SB-48	MSB-50
After setting su	ccessfully.slave	station respons	se message forr	nat:	200.00	200110	1100.000
Slave address	Function code	Address where	data is stored	Modify	/ value	Redundancy cl	neck CRC16-2
80	06	9C	73	MSB:00	LSB:00	LSB:48	MSB:50
The switch stat Modification ra For example:Th Th Th Return:If the se	us setting instructing instructing instructing in the sensor now water send commate sensor now water sensor now water send commatting is successful tring is successful in the sensor send commatting is successful in the sensor send commatting is successful in the sensor senso	tion is used to kinds) ants to set the s nds via RS485 b ants to set the s nds via RS485 b Il,the original ir	modify any curr witching value bus:80 06 9C 73 (witching value bus:80 06 9C 73 (nstruction will b	rent outpu to NPN 00 00 48 50 to PNP 00 01 89 90 e returned	it status to)) d;lf it fails,	o the required le	ogic value. ction will be ret
7.Master station	n request messag	ge format(Filter	r times setting):				
Slave address	Function co	de Address w	here data is store	d Mo	dify value	e Redundano	cy check CRC16-
80	06	90	77	MSE	3:00 LSB	:00 LSB:0	9 MSB:91
After setting su	ccessfully,Slave	station respons	e message form	nat:			
Slave address	Function co	de Address wi	here data is store	d Mo	dify value	e Redundand	cy check CRC16-

Slave address	Function code	Address where data is stored		Modify	value	Redundancy check CRC16-2		
80	06	9C	77	MSB:00	LSB:00	LSB:09	MSB:91	

The order of filter times is used to set any current filter times as the required filter value.

Modification range:Fast, Medium, Slow(three kinds). For example:He sensor wants to set the number of filtering times to fast(1st Filtering) Then send instructions via RS485 buss80 06 9C 77 00 00 09 91

He sensor wants to set the number of filtering times to medium(8st Filtering)

Then send instructions via RS485 bus:80 06 9C 77 00 01 C8 51 He sensor wants to set the number of filtering times to slow(20st Filtering) Then send instructions via RS485 bus:80 06 9C 77 00 02 88 50

Return: If the setting is successful, the original instruction will be returned; If it fails, an error If it fails, an error instruction will be returned.

8.Master station request message format(Reset):

	Slave address	Function code	Address where data is stored		Modify value		Redundancy check CRC16-2	
	80	06	9C	87	MSB:00	LSB:01	LSB:C8	MSB:62
After setting successfully,Slave station response message format:								
ł.	Slave address	Function code	Address where	data is stored	Modify	value	Redundancy ch	eck CRC16-2
	80	06	9C	87	MSB:00	LSB:01	LSB:C8	MSB:62

The reset Settings command is used to restore factory Settings.

Send instructions:80 06 9C 87 00 01 C8 62 Return: If the setting is successful, the original instruction will be returned; If it fails, an error If it fails, an error instruction

will be returned.

9.Error feedback

Address and CRC check errors will not receive the slave data feedback, other errors will be returned to the host error code. The second (function code) of the data frame plus 0X80 indicates an error in the request(illegal function code, illegal data value), If the second part of the data frame (function code) plus 0X80 is greater than 0XFF, the second part returns 0XFF.

).The following	gerror instruction	is returned(illegal	function code):

Slave address Function code Error code Redundancy check CRC16-2 80 91 01 LSB MSB If the function code is not 0X03 or 0X06, the function code is invalid

For example: Send instructions: 80 11 9C 74 00 00 8D 92 Return: 80 91 01 DC 78

Send instructions:80 88 9C 74 00 00 91 8E Return:80 FE 01 F0 18 (2).he following error instruction is returned(illegal Register address):

	-					
	Slave address	lave address Function code		Redundancy ch	eck CRC16-2	
	80	86	02	LSB	MSB	
1						

When the register address is wrong, it is considered an illegal function code. For example:Send instructions:80 06 9C 00 00 00 B9 8B Return:80 86 02 93 89 (3).he following error instruction is returned(illegal data value):

-			-			
	Slave address Function cod		Error code	Redundancy check CRC16-2		
	80 86		03	LSB	MSB	

When the register address is wrong, it is considered an illegal Data value

03 02 MSB LSB LSB MSB

The slave response message:80 03 02 09 A1 43 B2

The 4th and 5th bytes of the slave's response message are 09 A1, converted to decimal 2465,

Slave address	Function code	Address where	data is stored	Data volume (l	Jnit: words)	Redundancy check CRC16-2	
00	06	9C	7E	00	81	06	33
The address breadcast call command is used when the address originally set by the senser is unclear Medify any							

current address value ton the required value through broadcast command. Address modification range:0x80~0xF4

Then send instructions via RS485 bus:00 06 9C 7E 00 82 46 32

3.Master station request message format(Modified address command):									
Slave address	Function code	Address where data is stored		Modify value		Redundancy check CRC16-2			
80	06	9C	7E	00	85	LSB:18	MSB:30		
ilave station response message format:									
Slave address Function code Address where data is stored Modify value Redundancy check CRC16-2							ck CRC16-2		
80 06 9C 7E 00 85 LSB:18 MS									
The modification is invalid if the modified address is out of range.Return error instruction:									







*For mounting, please keep tightening torque < 0.5N · m

PS-PDB-2023LB V3

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